LCGT Seismic attenuation Present Status

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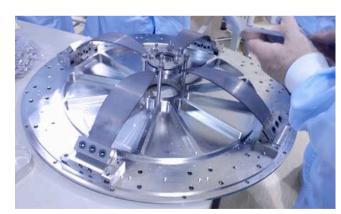
A. Takamori, T. Uchiyama, K. Yamamoto

LCGT standard filter

- Last time the standard filter went from a design:
- To a prototype.

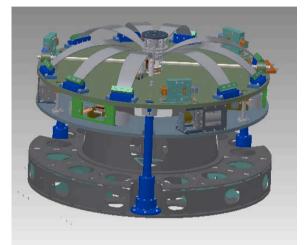
- Tested at NIKHEF
- Now under test in the basement at Kashiwa



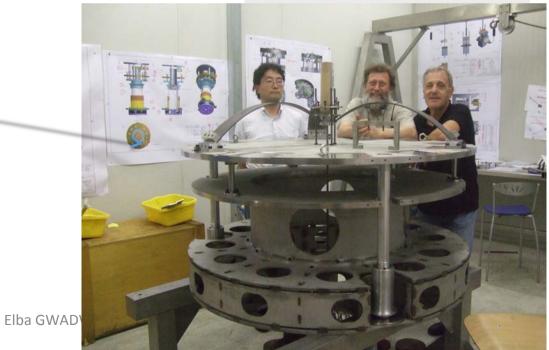


Inverted pendulum-Top Filter

We went from a design



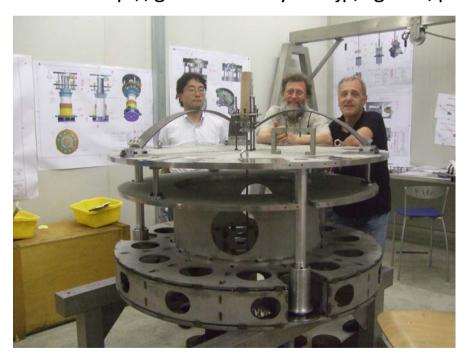
To a prototype

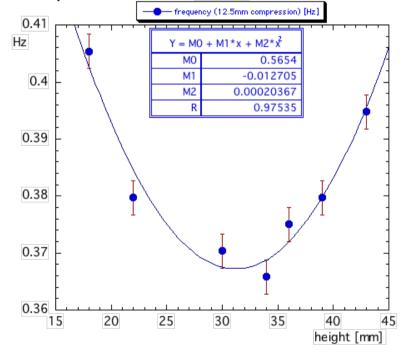


Top Filter / Inverted Pendulum

- Very preliminary tests at G&M
- For more detail please see:

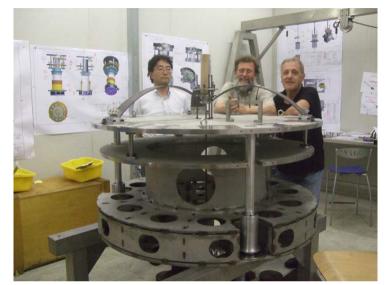
http://gw.icrr.u-tokyo.ac.jp/cgi-bin/private/DocDB/ShowDocument?docid=452



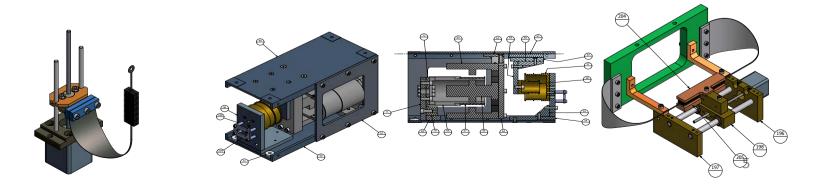


Top Filter / Inverted Pendulum

- Now installing
 - LVDT,
 - voice coil actuators,
 - stepper motor springs

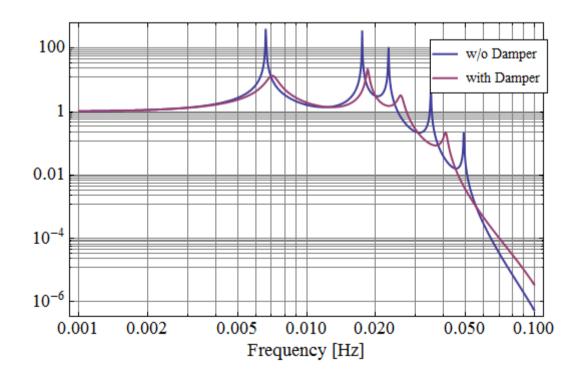


Then shipping to Kashiwa



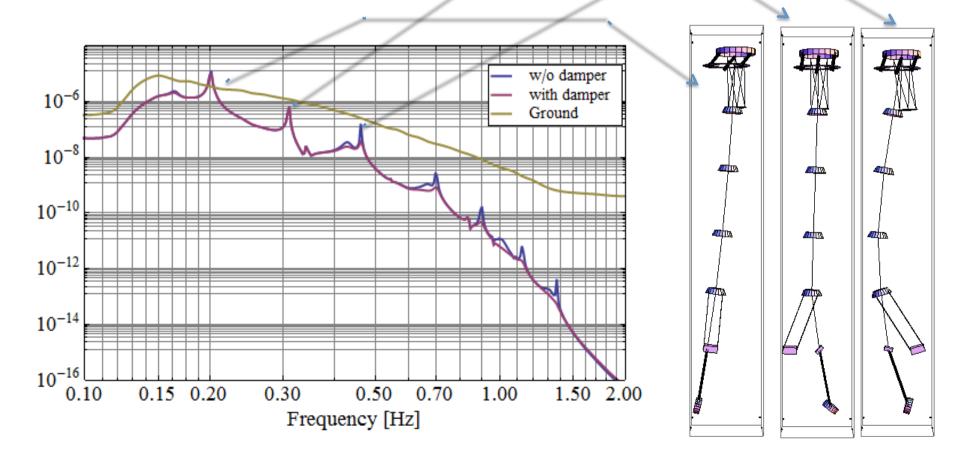
Simulations: Yaw motion

- The transfer function from ground yaw motion to TM yaw motion shows:
- Good damping can be achieved



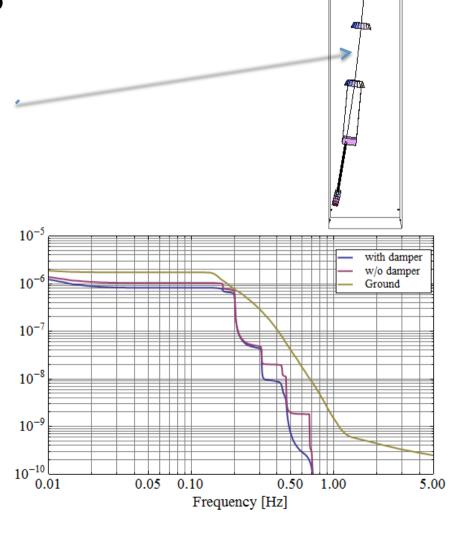
Simulation: Transversal modes

 seismic noise level of TM, with/without eddy current damping



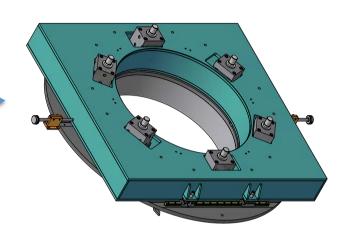
Damping of lower modes

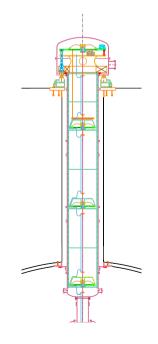
- Active damping for RMS amplitude reduction
 - try using shadowmeter signal
 - Otherwise accelerometer signal
- For easier lock acquisition



Presently under Development

- Inverted pendulum support structure
 - Top of type A
 - Top of type B
- Cabling
- Safety structure
- Installation procedure down the well





What will be achieved

- All construction blocks for the LCGT seismic attenuation will have been prototyped
- Type A seismic attenuation designed

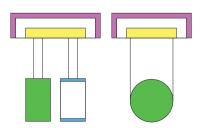
To do

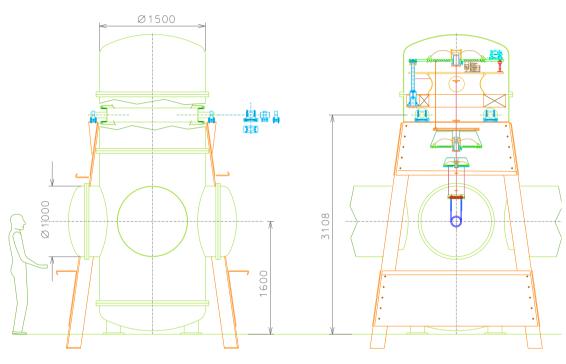
- Intensive performance tests at Kashiwa
- Validation of simulations
- Evaluate cabling performance degradation

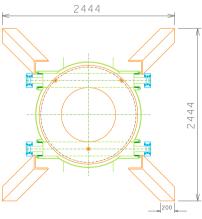
Start simulating controls

What next

- Design of type-B
- Inverted
 pendulum table
 on space frame
 surrounding
 vacuum chamber
- Type B payload

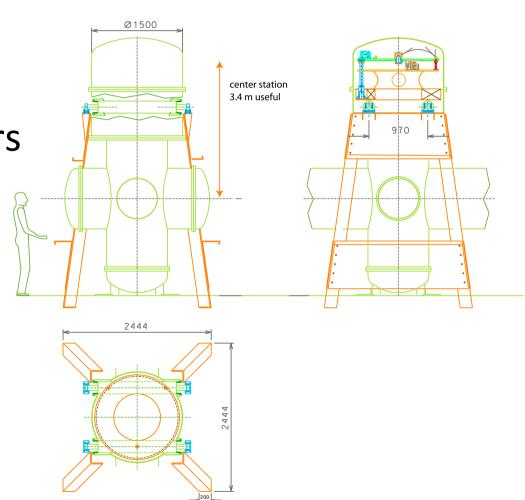






What next

 Adapt design for tests with TAMA vacuum chambers



And then

Return to payload design for i-LCGT

 Interface with cryogenics

