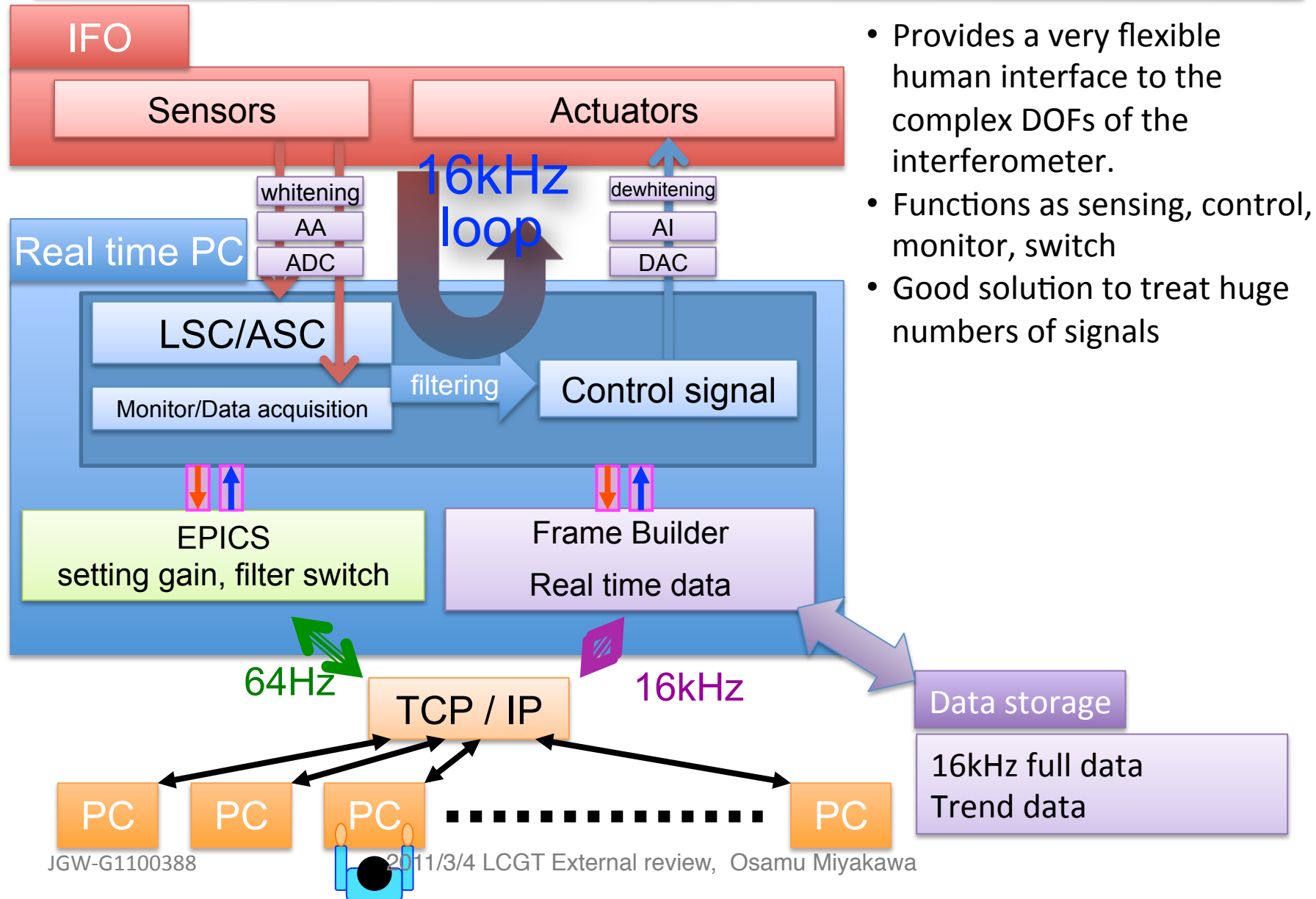




Concept of the digital system





Global and internal requirements

Global requirements

- Observation bandwidth >5kHz
- Dynamic range >120dB
- Control bandwidth >200Hz
- Number of channels >1024
- Number of output channels >256

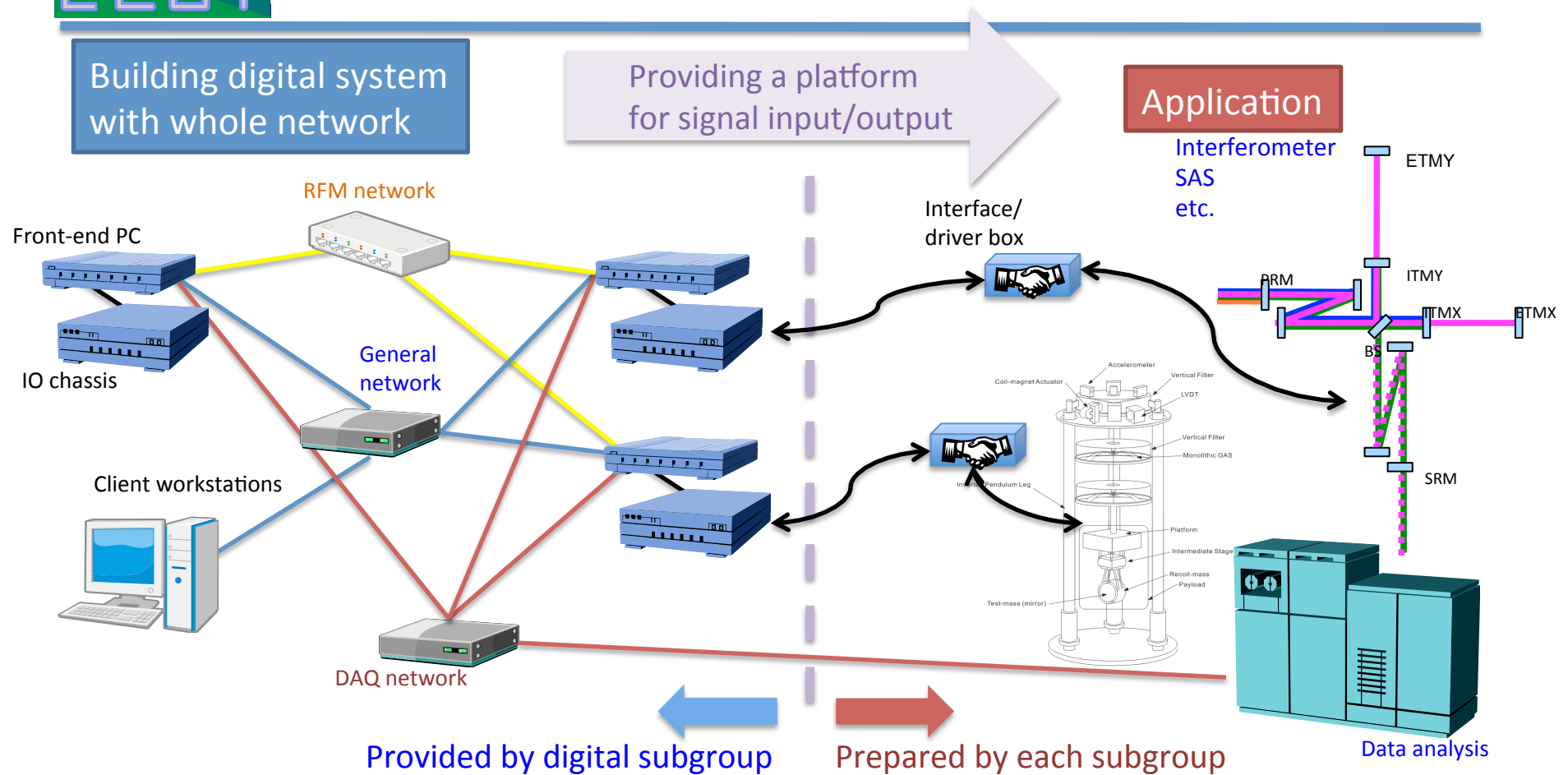
Internal requirements

Item	Requirements	Comment
Sampling rate	$\geq 16384\text{Hz}$	65536Hz at ADC, then decimated to 16384Hz
ADC bit resolution	$\geq 16\text{bit}$	
Dynamic range of input	$\geq \pm 15\text{V}$	Differential input
Dynamic range of output	$\geq \pm 10\text{V}$	Differential output
ADC noise	$< 3\mu\text{V}/\text{rHz}$	Effectively reduced by whitening filter
DAC noise	$< 3\mu\text{V}/\text{rHz}$	Effectively reduced by dewatering filter
time delay	$< 100\mu\text{sec}$	For >200Hz UGF
Input channel numbers	$> 2048\text{ch}$	(16kHz: >128ch, 2kHz: >512ch, 64Hz >1024ch)
Output channel numbers	$> 512\text{ch}$	For mirrors, seismic attenuators, PZTs etc.
Stored channel numbers	16kHz: >64ch, 2kHz: >512ch, 64Hz >1024ch, 16Hz >10000ch	$\sim 300\text{TB}/\text{year}$

Provides a robust and flexible platform to IFO and all subsystems for **control, monitor, diagnostic, switch** during **installation, commissioning, operation, observation**



Overview of digital system subgroup



- Real time system
- PC, software
- ADC/DAC/BO, AA/AI
- DAQ/RFM/timing network

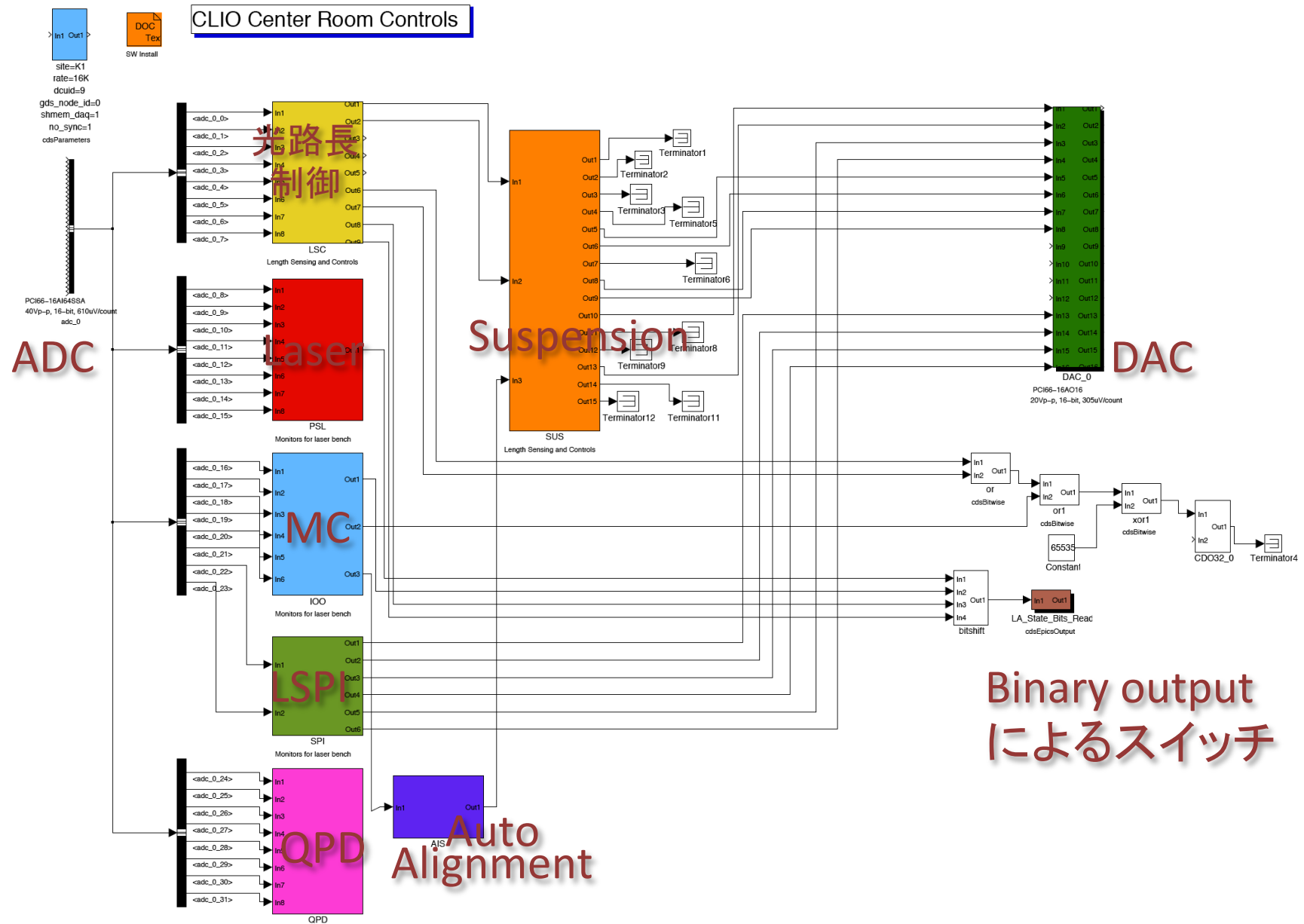
- Control, monitor, switch
- Auto lock, auto alignment
- Commissioning, noise hunting
- Diagnosis, tuning, calibration
- Operation, observation



Hardware and software

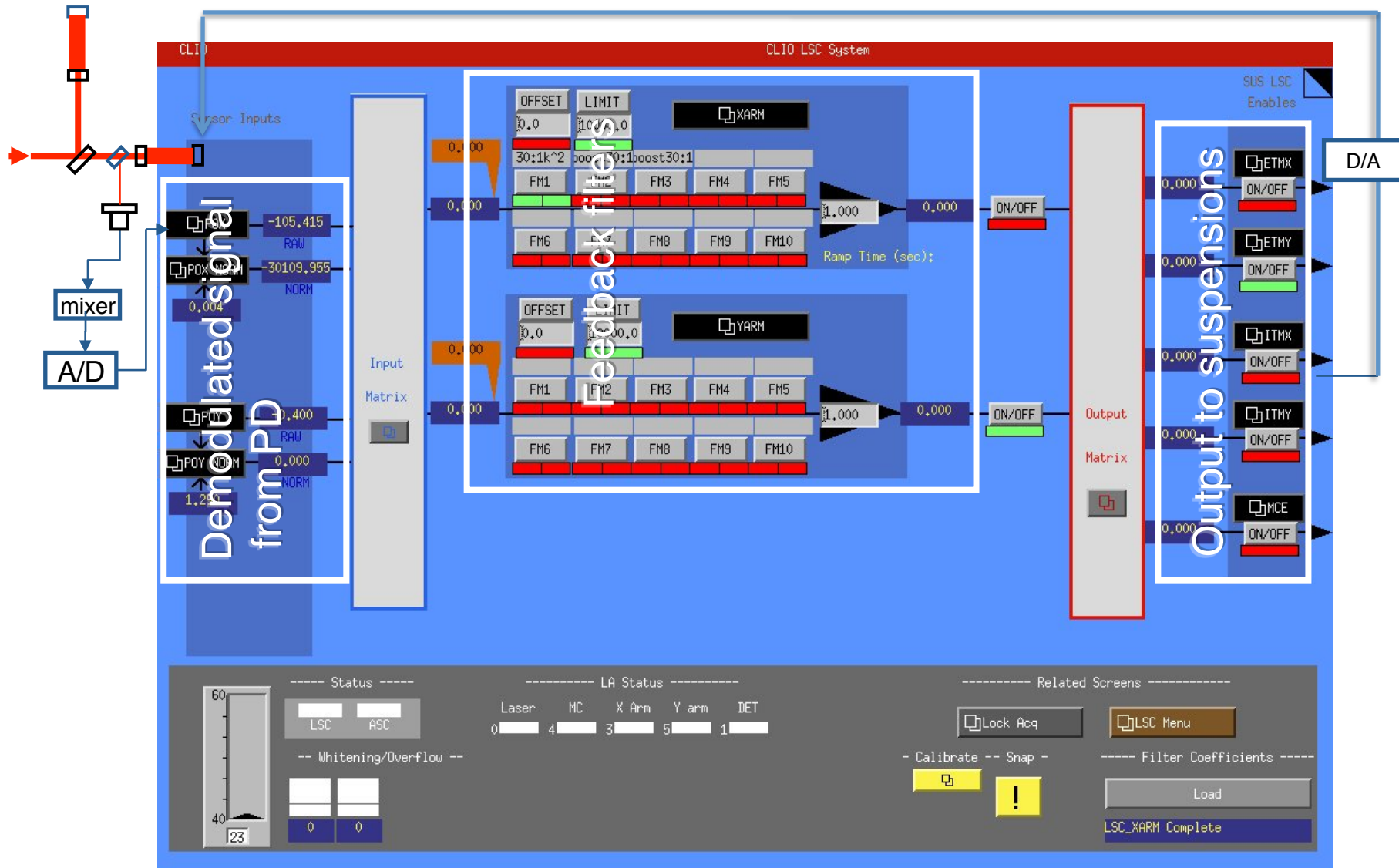
1. Dual x86 processors, with four CPU cores each.
2. Processor clock speed of 3GHz.
3. Eight (8) Gigabyte of memory.
4. Two Gigabit Ethernet interfaces.
5. One, or more, real-time network interfaces
 - Reflected Memory (RFM)
 - PCI Express (PCIe) network interface
6. A PCIe interface to the PCIe expansion chassis with a maximum of 14 PCIe cards installed.

Real time code on Matlab, Simulink





MEDM --Length sensing and control system



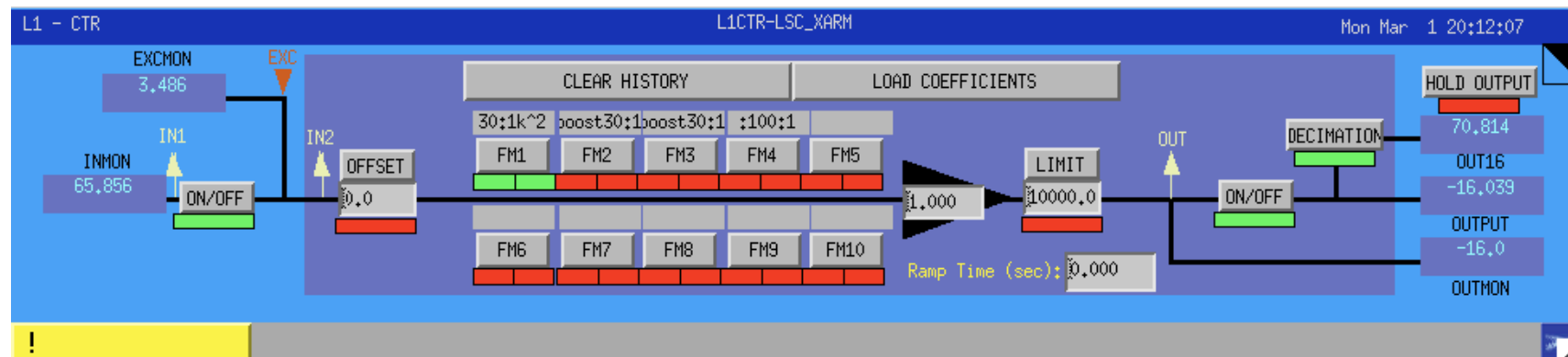
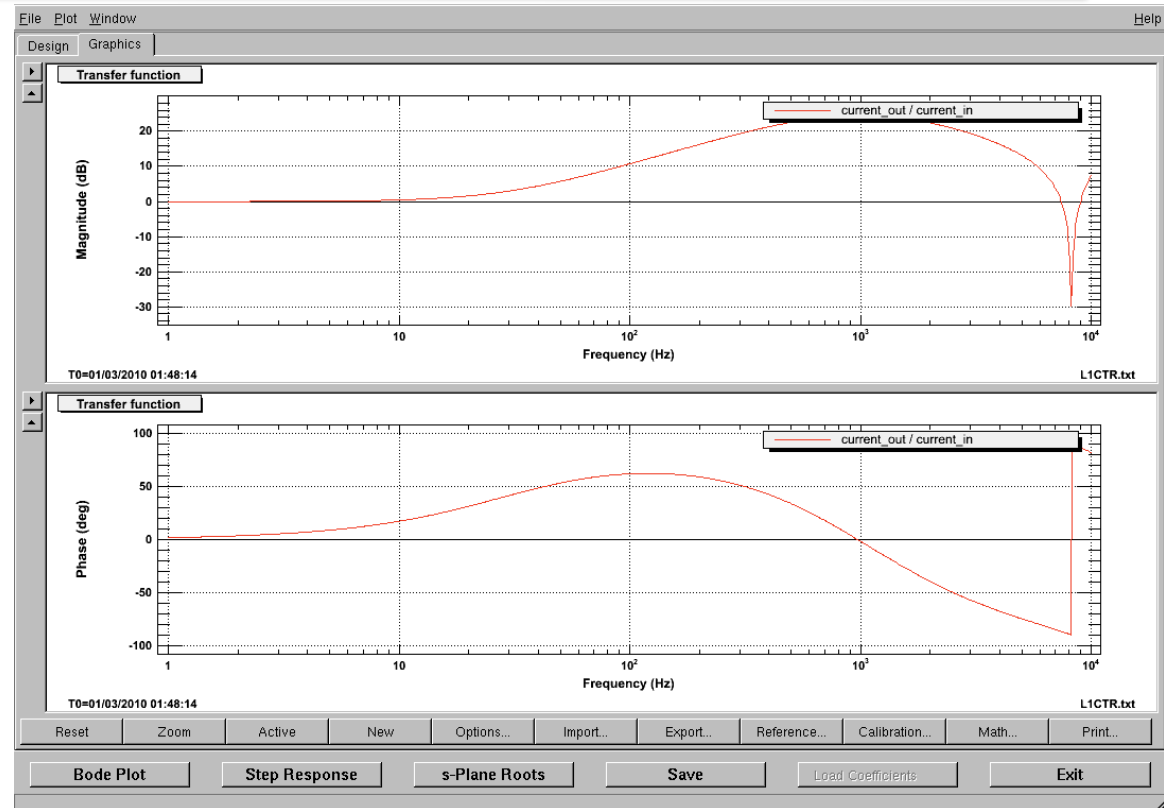


Monitor/diagnosis software

- Dataviewer: oscilloscope,
- DTT: FFT analyzer
- Foton: digital filter composer
- Ezcademod: digital modulator/demodulator
- Foton: GUI digital filter composer

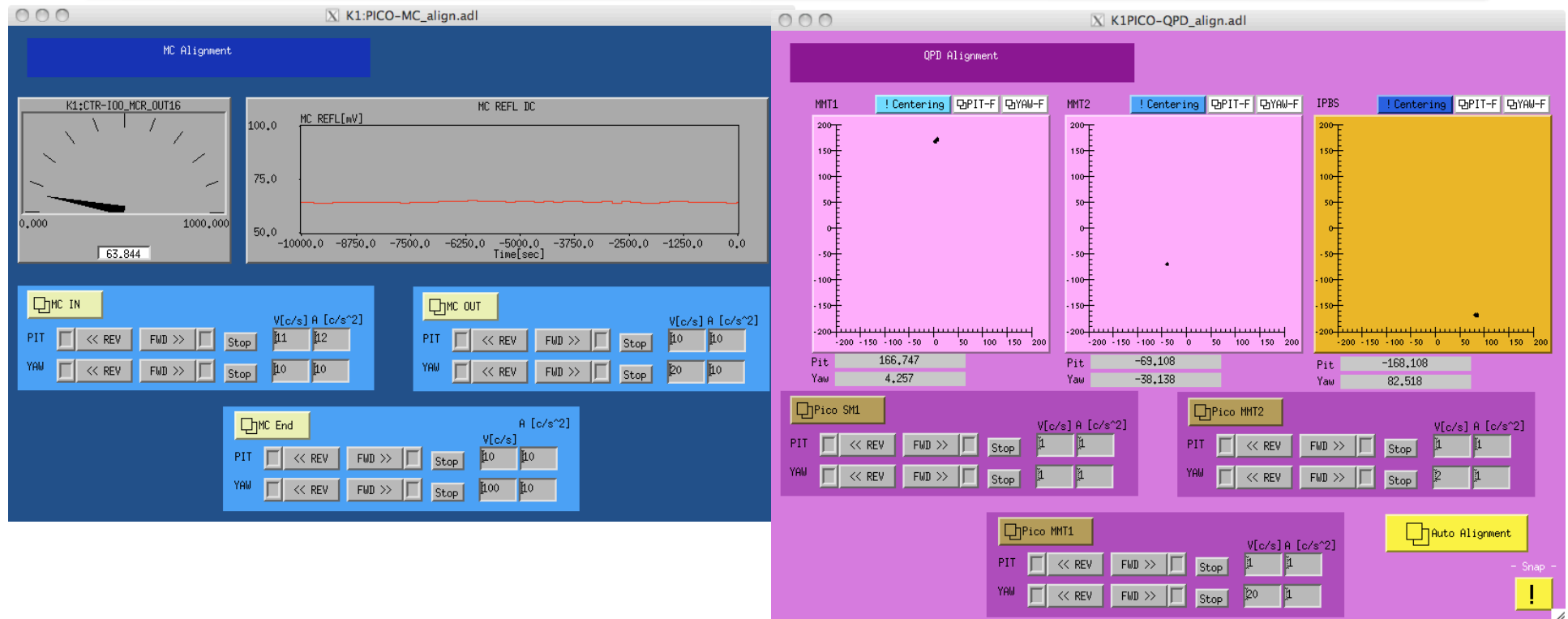
Filters on MEDM

- Signal excitation
- 10 filter banks
- 3 monitor point IN1/IN2/OUT





QPDを利用した自動入射ビームアライメント



##MMT1 QPD centering

#pitch

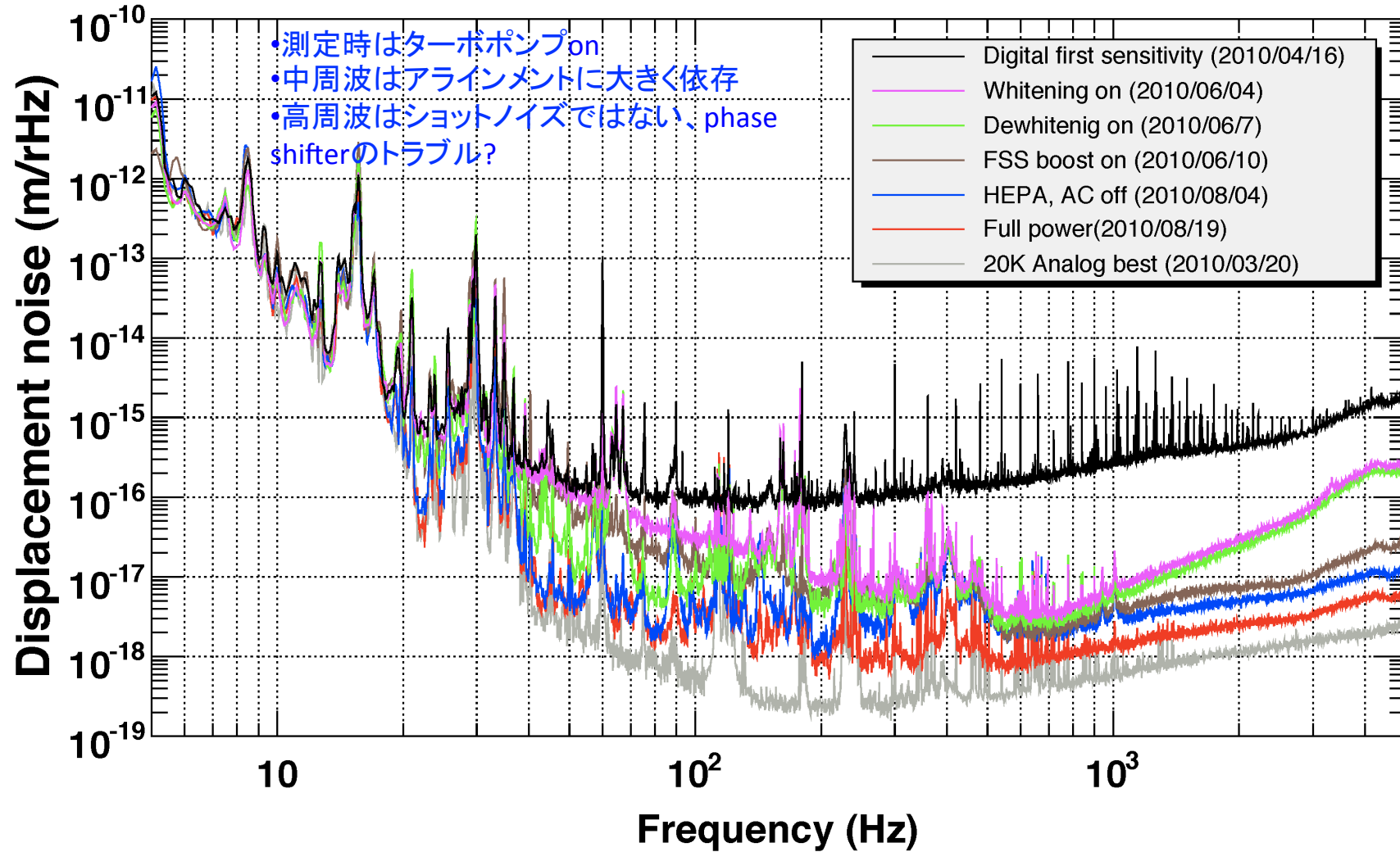
```
python /cvs/cds/kami/scripts/AutoAlignment/DitherAlignment.py --freq 5 --excGain 0 --fbGain 0.1 --readBackChan
"K1:CTR-AIS_MMT1_PIT_OUT16" --feedBackChan "K1:PICO-SM1_PIT" --successCond 10 --fbWait 1 --timeout 120
```

#yaw

```
python /cvs/cds/kami/scripts/AutoAlignment/DitherAlignment.py --freq 5 --excGain 0 --fbGain 0.005 --readBack
Chan "K1:CTR-AIS_MMT1_YAW_OUT16" --feedBackChan "K1:PICO-SM1_YAW" --successCond 40 --fbWait 1 --timeout 60
```

Digital制御での現CLIO感度

CLIO sensitivity



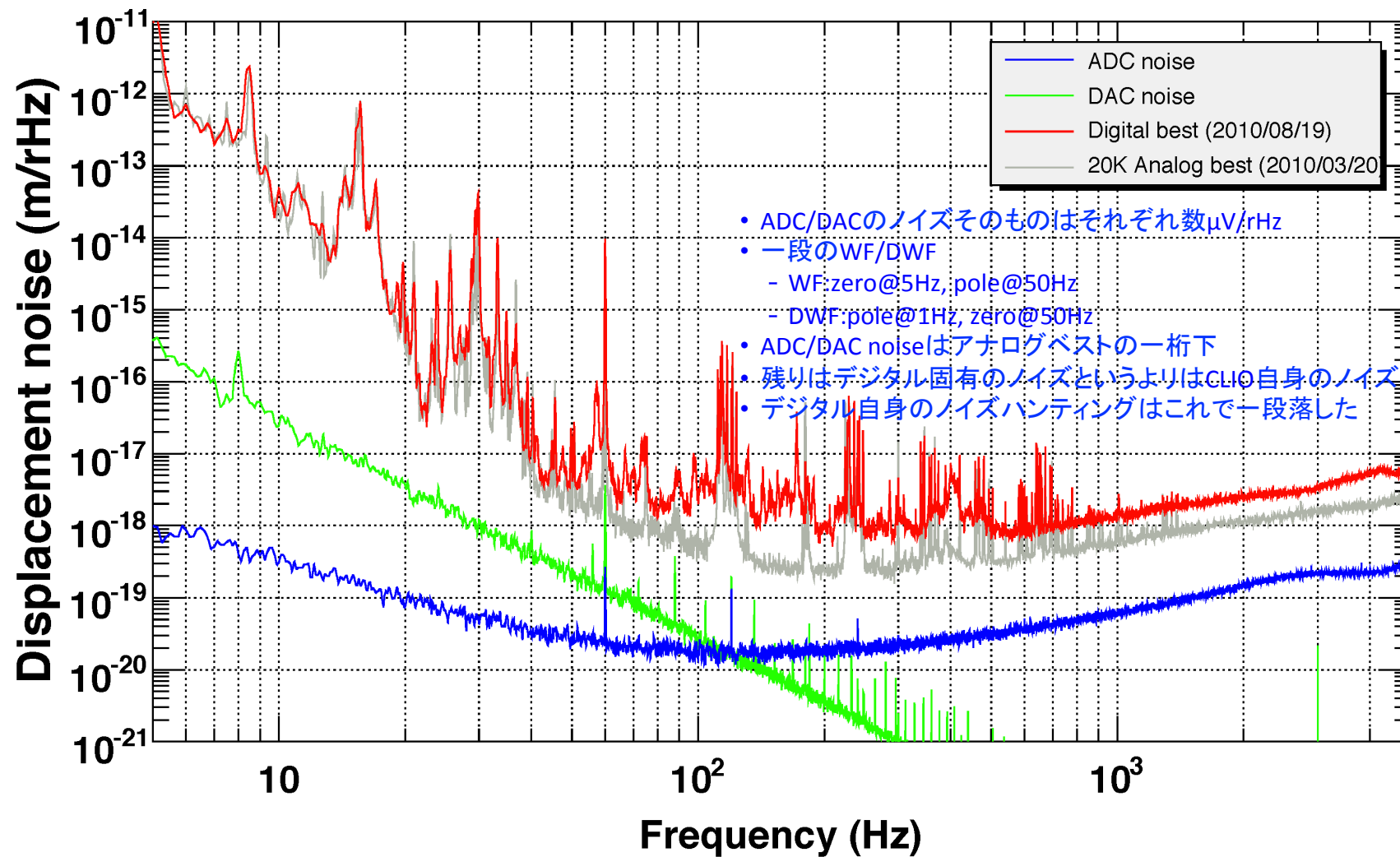
*T0=16/04/2010 05:37:10

*Avg=1/Bin=4L

*BW=0.187493

AD/DAC noise

CLIO sensitivity



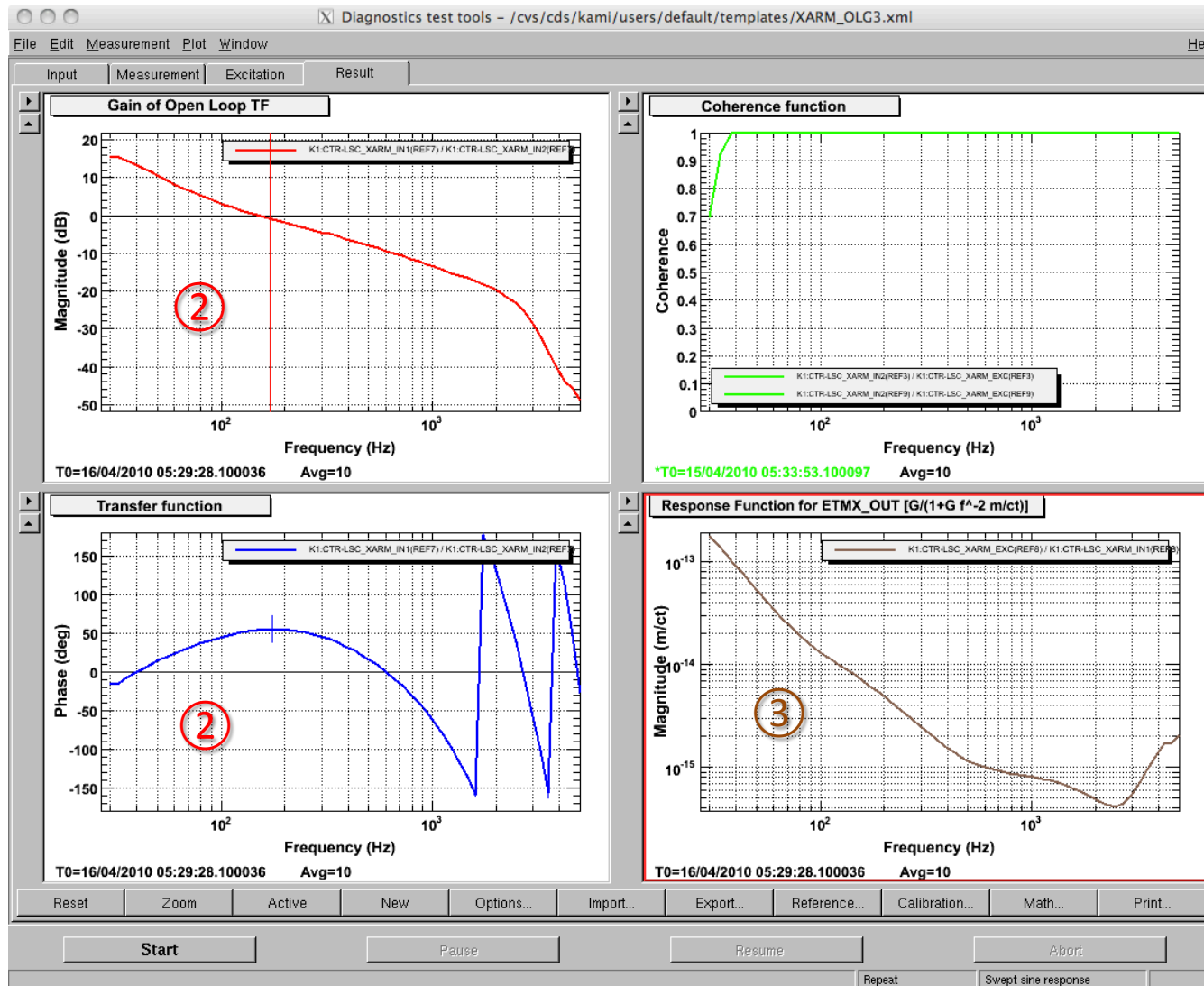
*T0=08/09/2010 01:16:38

*Avg=17/Bin=4L

*BW=0.187493



Calibration



1. ロック中、サスペンションアクチュエータ直前のノイズ①をデジタル内で測定

2. Open loop TF:Gを測定②

3. ②を $(1+G)/G \cdot f^{-2} \cdot m/ct$ に変換③

4. Calibrated noise: ① * ③
(前ページの図)

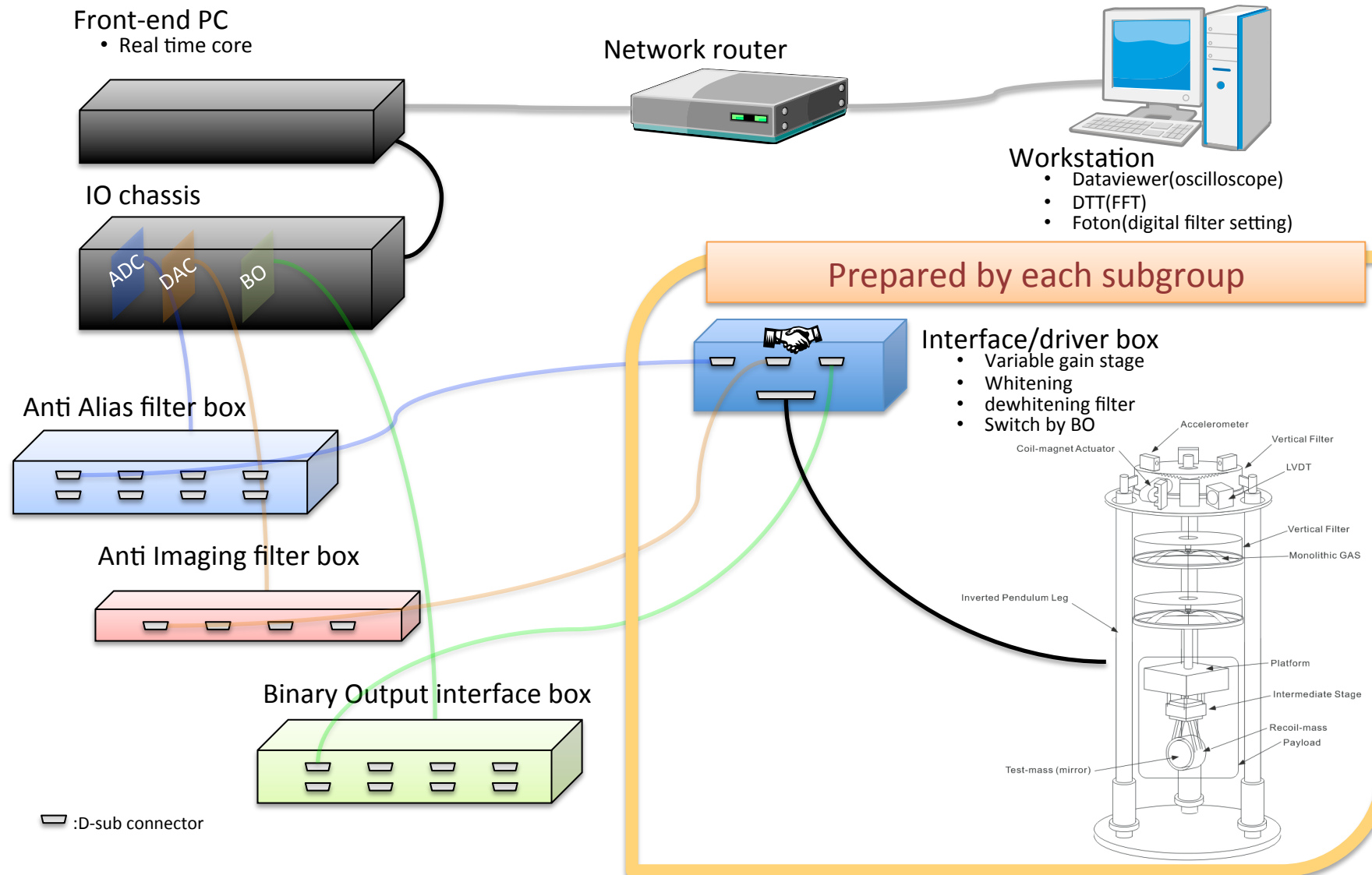
5. 次回以降CalibrateしたいときはUGFを常に同じになるように制御ゲインを調整すればよい

→ 常時感度モニタの実現

- UGFより低い周波数ではフィルターの形を任意に変えてもOK(高い周波数を変えたらOLTFの再測定)
- ノイズ測定ポイント以前ではゲインを変えても構わない(測定点以降のゲイン変化は補正が必要)



Connecting subsystems into digital system





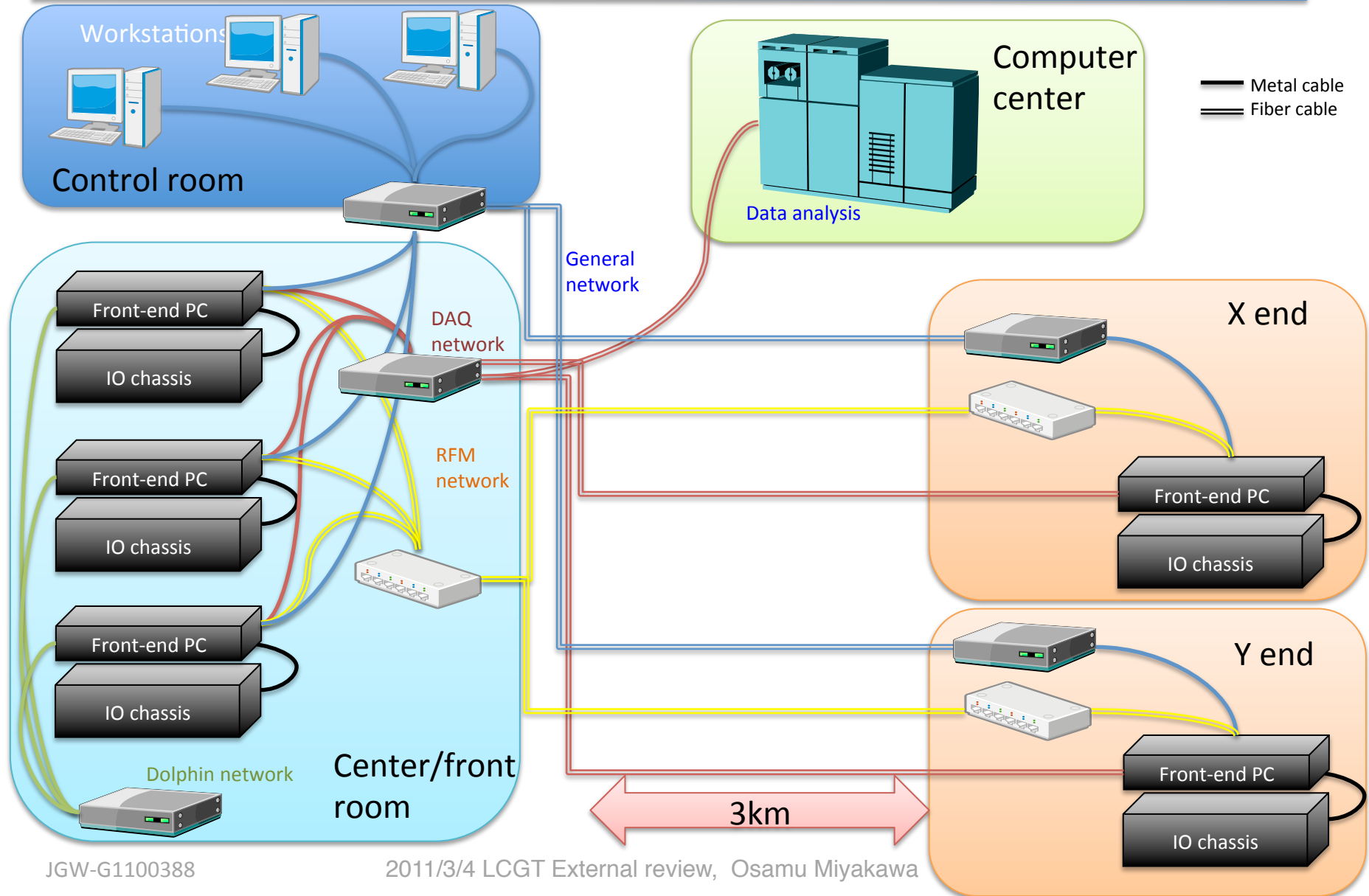
Interface

- ADC 32ch/card
 - 16kHz sampling
 - With Anti Alias filters
 - 2uV/rHz
 - D-sub 9pin(for 4ch, differential), +/-20V input
- DAC 16ch/card
 - With Anti Imaging filers
 - 1.5uV/rHz
 - D-sub 9pin(for 4ch, differential), +/-10V output
- BO 32ch/card
 - D-sub 9pin(for 4ch, differential), 0 or +5V output
 - Ex. Variable gain amp for 16 steps/1 D-sub connector

Note: D-sub 37pin may be supported for all input/output

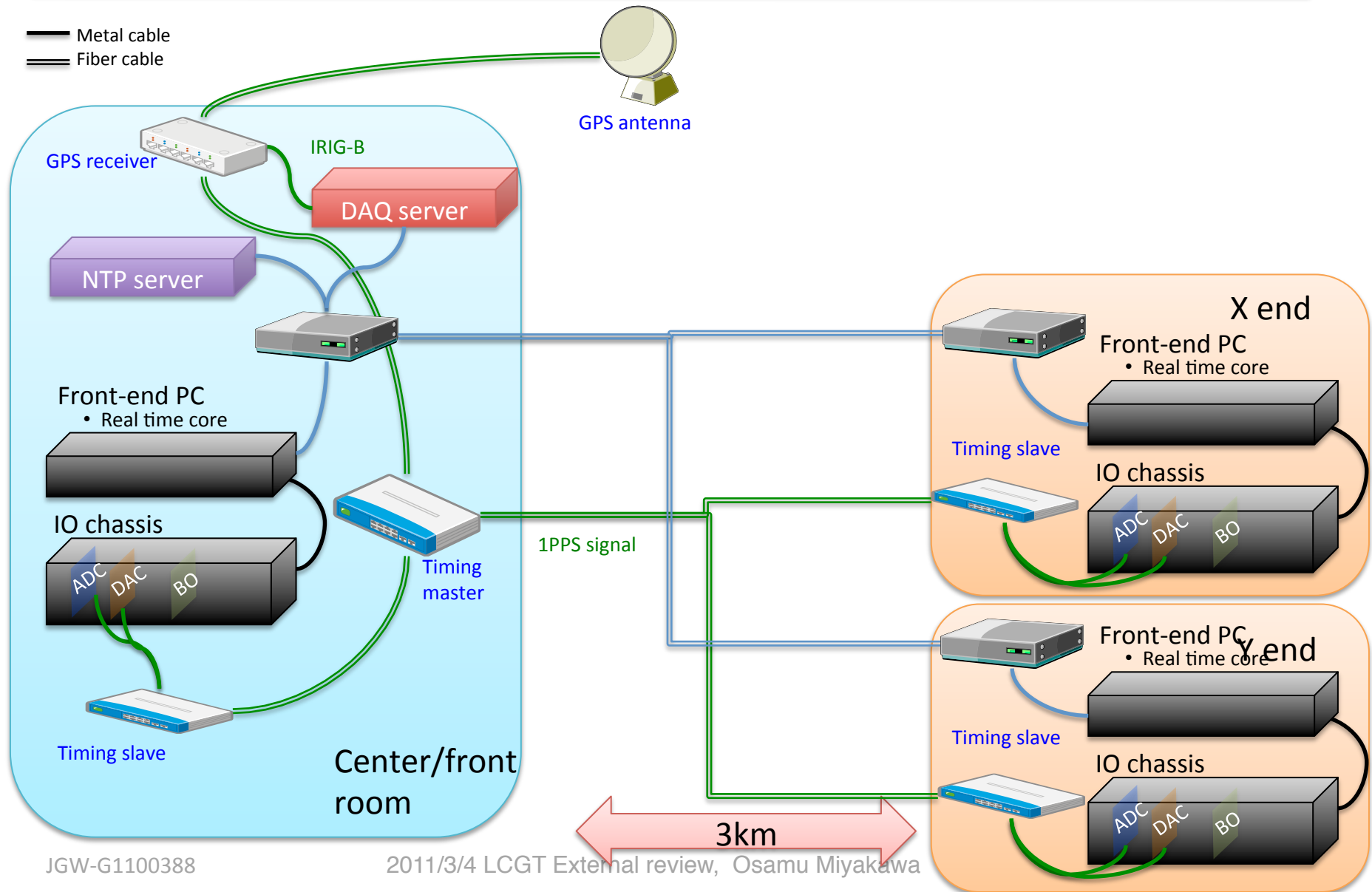


Network design





Timing Network





Making channel lists

- Needs channel list for ADC/DAC/BO
 - ADC input ~2048ch
 - will be categorized as class1(IFO main), class2(IFO sub), class3(PEM, physical environment monitor)...
 - DAC output: ~512ch
 - BO: ~2048ch
- DAQ channel: stored signals to data storage as 16kHz, 2kHz, 64Hz...



DAQ Channel list

	Number of stored channels	Data acquisition, Data analysis, IFO control	16kHz:64ch, 2kHz:512ch, 64Hz:1024ch 16Hz:16384 epics channels (see channel list)
*	Data bit resolution at ADC/DAC	Data acquisition	16bit = 65535
*	Data bit resolution in PC	Data acquisition	32bit = 4 Byte integer
	Data transfer rate	Data acquisition	4MB/sec for 16kHz, 4MB/sec for 2kHz, 128kB/sec for 64Hz, 1MB/sec for 16Hz, Total ~10MB/sec ~30GB/hour ~1TB/day ~300TB/year

6. Channel list

a. 16kHz (total 64ch)

Part	Channel point	Channel number	Description
Laser	Output laser power[W]	1	
	IFO Input laser power[W]	1	
MC	REFL	1	
	MC length feedback	1	
	MC frequency feedback	1	
LSC	I&Q for DARM, CARM, MICH, PRC, SRC, etc.	10	
	error, feedback	10	
SUS	length * 10 suspensions	10	

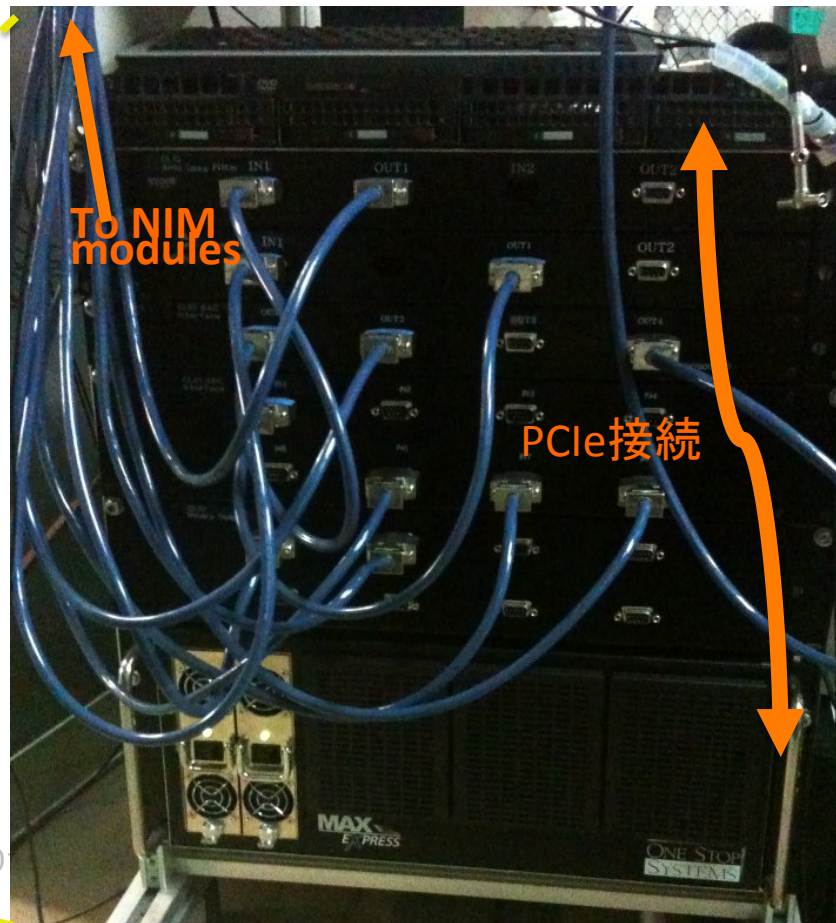
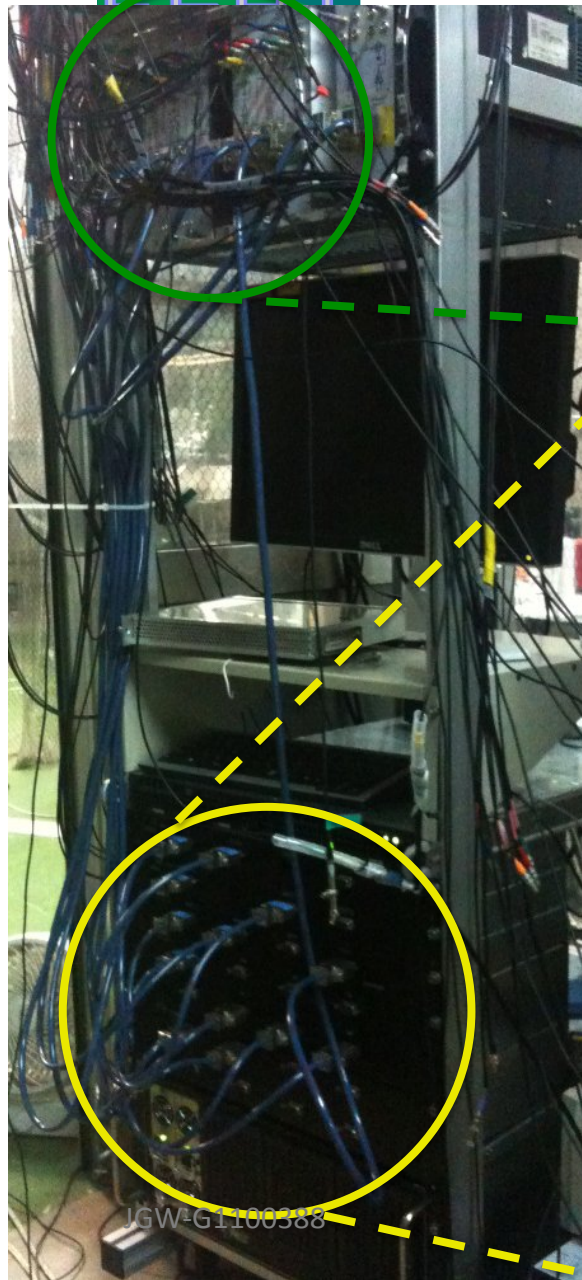
b. 2kHz (total 256ch)

Part	Channel point	Channel number	Description
ASC	WFS	5xpitch, yaw=50	
	Oplev	10xpitch, yaw=100	

c. 64Hz Long term monitor (total 512ch)

Part	Channel point	Channel number	Description
Temperature[deg]	room	10	center, end, arm
	table	10	laser, REFL, AS, pickoff, end
	suspensions	50	Low temperature
	mirrors	50	Low temperature
Humidity[%]	rooms	10	center, end, arm
Dust	rooms	10	center, end, arm
Laser	crystal temperature[degree] and etc.	10	
	Master laser power[W]	2	

Pictures



Real time PC
CentOS 5.2+real time kernel
4core x 2 Xeon

Anti Imaging filters
Anti Alias filters

DAC adapter

ADC adapter

Binary output adapter

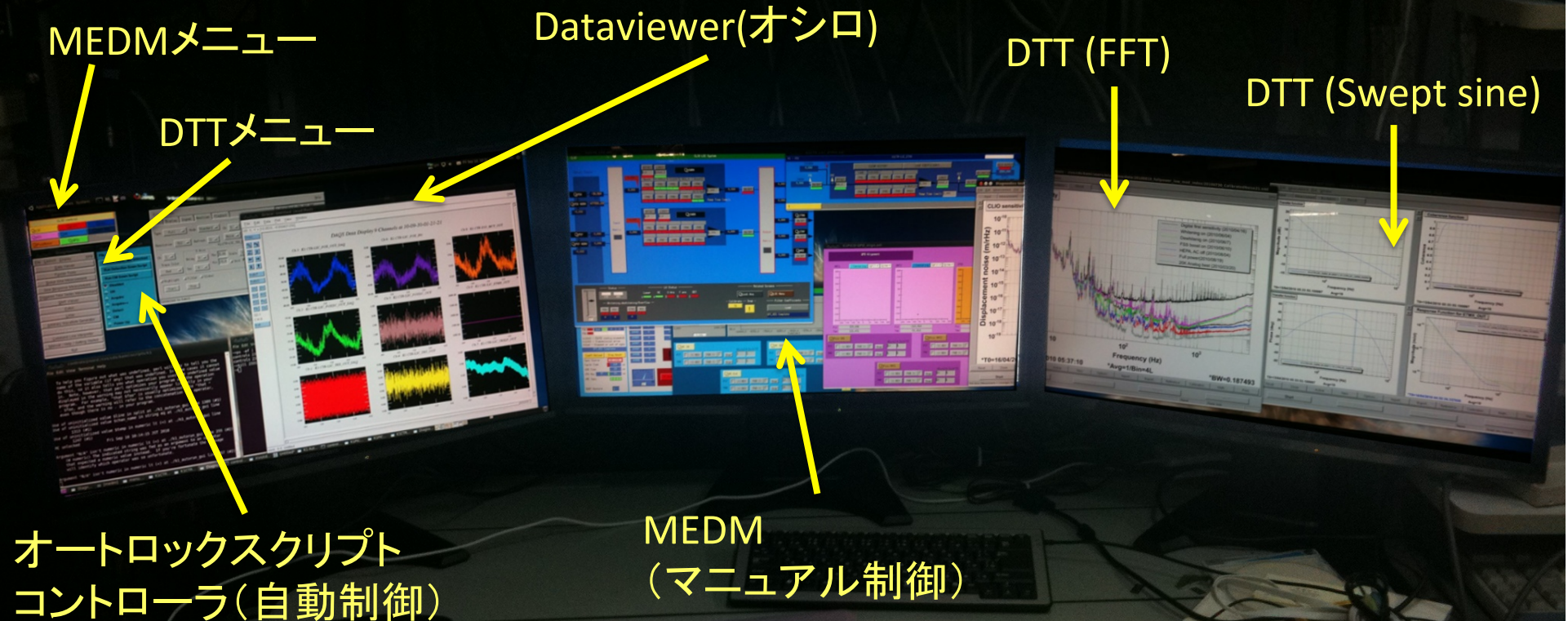
ADC/DAC
In Expansion Chassis

ADC:32ch/\$4K

DAC:16ch/\$3.5K

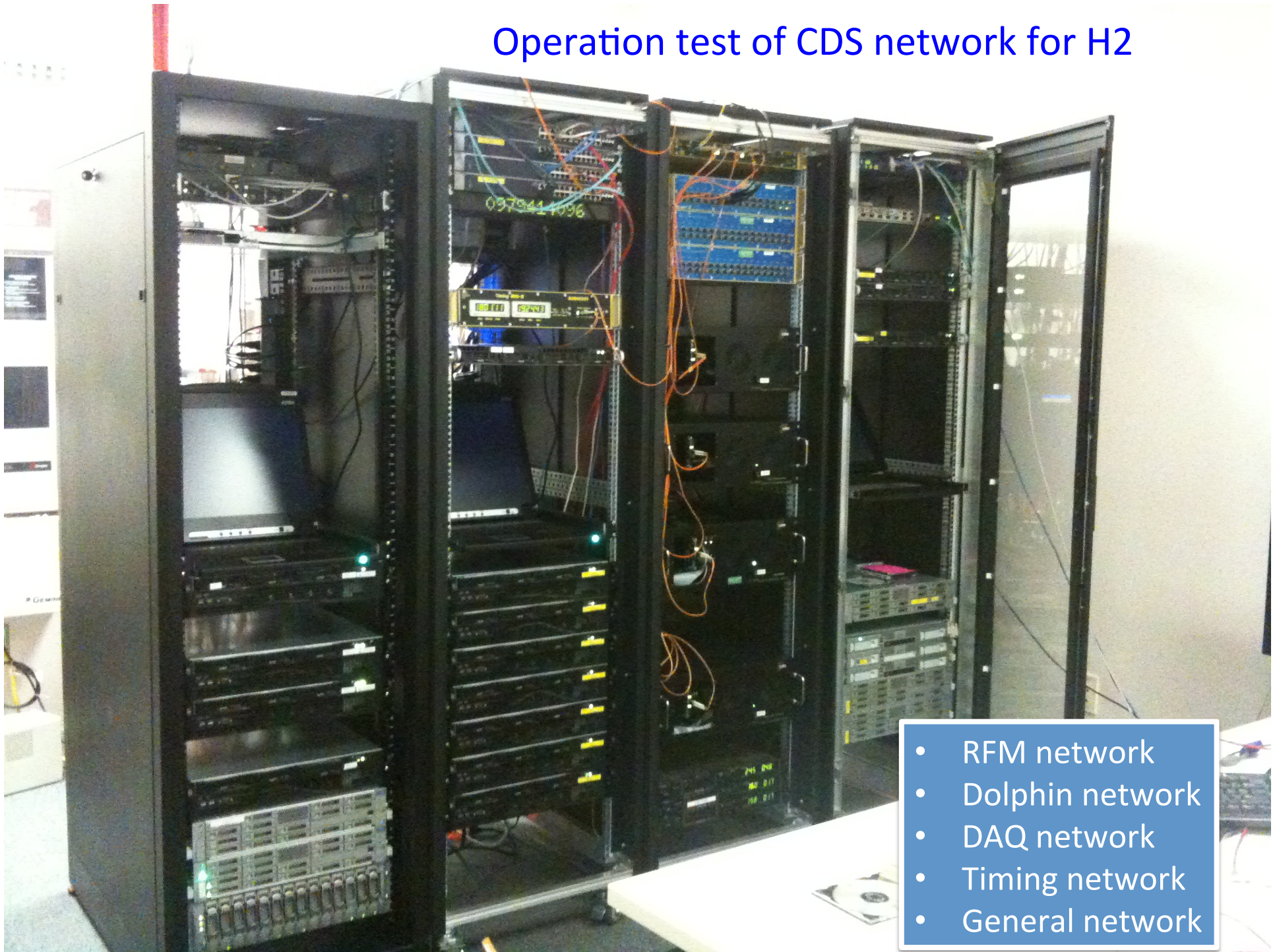
Binary Output:32ch/\$250

Client system



- スクリプトにより自動でロックし、測定、改善するという体制ができつつある

Operation test of CDS network for H2



- RFM network
- Dolphin network
- DAQ network
- Timing network
- General network